

Enabling a World of Applications

IIIRoboG4™

MEDICAL ROBOTS

MOBILE ROBOTS/AGV

• MULTI-ACCESS ROBOTS

ELECTRIC WATERCRAFT

AGRICULTURAL ROBOTS

MATERIAL HANDLING & LOGISTICS

AUTOMATED PRODUCTION & TEST MACHINERY

Roboteg drives have the feature sets that make them well suited in a wide range of advanced motion control applications: precise speed, torque, and position control; exceptional power density, dual-channel, battery operation support, regenerative braking, fieldbus connectivity, rugged construction, Functional Safety and advanced protection of the enabling technologies found in our RoboG4 drives.





Advanced Servo Drives & Integrated Motors



RoboG4 is Roboteg's fourth generation family of low voltage (under 100 Volts) servo drives.

The RoboG4 range includes three main families of single-channel and dualchannel drives from 1500W to 19kW max. A major new addition is an integrated unit that merges Roboteg's motion control technology with Nidec's servo motor expertise. RoboG4 drives deliver world-class performance, Functional Safety, and exceptional connectivity to all major fieldbuses. All RoboG4 drives are compatible with each other, and so can scale to meet the needs of most applications.



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Engineered for Your Success



RoboG4 drives include automatic field weakening, allowing the motor to reach a significantly higher speed than its maximum rating, or produce additional torque at the motor's rated top speed.



Faster Processing

New, faster and best-in-class motion algorithms.



Adapt Automatically to Load Changes

Adaptive control continuously observes the system's inertia and applies new gains on the fly, resulting in optimal performance at any load point.



Ultimate Precision and Control

Current is measured and adjusted every 62 microseconds to produce smooth and precise torque, while always operating within safe ranges. Three cascaded loops for position, speed and current, each with its own PID and Feed-forward gains, resulting in easier tuning, and optimal performance and system responsiveness.



Overcome Mechanical Constraints

RoboG4 drives incorporate a notch filter which reduces vibration due to mechanical resonance. A mechanism has been added to compensate for the magnetic cogging caused by the rotor teeth and the permanent magnets inside the motor, and smooth out the rotation at very slow speeds.



Stay Ahead of Technology

Protect your investment with our drives and leading-edge motion control technology. Get the most of any motor types. RoboG4 drives have the necessary circuitry and control algorithms for today's most popular motor types: Surface Permanent Magnets (SPM) or Internal Permanent Magnets (IPM) brushless motors, DC brushed motors, and AC Induction motors.











S1-Series Compact Low-Power Single-Channel





	SBLG1360T	SBLMG1360T	
Power	OBEO 13001	ODEMIO 1300 I	
Number of Channels	1	1	
Max Amps/ch	30	40	
Cont Amps/ch	20	20	
Max Voltage	60	60	
Power Connections	Screw Terminal	Fast-on	
STO	Y	Y	
Communication	•	•	
RS232	Υ	Υ	
RS485	•	•	
CANbus	Υ	Υ	
Ethernet		-P versions	
Profinet		-P versions	
EthernetIP		-I versions	
EtherCAT		-C versions	
Rotor Sensor		-0 (01310113	
Encoder	Υ	Υ	
Hall	Y	Y	
Sin/Cos	Y	Y	
SSI Single-turn	Y	Y	
SSI Multi-turn	Y	Y	
Resolver	•	Y	
Sensor Connector	JST-PH	Molex Nanofit	
Input/Outputs	001111	WOICK HAITOIT	
Max Analog Inputs	6	6	
Max Digital Inputs	6	6	
Max Pulse Inputs	6	6	
Max Digital Outputs	2	2	
PWM Brake Outputs	_	1	
Brake Resistor Outputs		1	
I/O Connector	DSub15	Molex Nanofit	
Mechanical			
Dimensions	70x70x27mm	70x70x27mm	
Cooling	Conduction	Conduction	
IP Rating	IP40	IP40	
	www.roboteg.com		

S2-Series Compact Low-Power Dual-Channel





Number of Channels				
Max Amps/ch 30 (60) 30 (60) Cont Amps/ch 20 (40) 20 (40) Max Voltage 60 60 Power Connections Screw Terminal Molex Megafit STO Y Y Communication Y Y RS232 Y Y RS485 Y Y CANbus Y Y Ethernet Profinet EthernetlP EthercAT Rotor Sensor Y Encoder Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 8	Power			
Cont Amps/ch 20 (40) 20 (40) Max Voltage 60 60 Power Connections Screw Terminal Molex Megafit STO Y Y Communication Y Y RS232 Y Y RS485 Y Y CANbus Y Y Ethernet Profinet EthernetIP EthernetIP EthercAT Rotor Sensor Encoder Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs 8 8 Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 8	Number of Channels	2 (1)	2 (1)	
Max Voltage 60 60 Power Connections Screw Terminal Molex Megafit STO Y Y Communication Y Y RS232 Y Y RS485 Y Y CANbus Y Y Ethernet Profinet EthernetIP EthernetIP EthercAT Rotor Sensor Encoder Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs 8 8 Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit <td>Max Amps/ch</td> <td>30 (60)</td> <td>30 (60)</td>	Max Amps/ch	30 (60)	30 (60)	
Power Connections Screw Terminal Molex Megafit STO Y Y Communication Y Y RS232 Y Y RS485 Y Y CANbus Y Y Ethernet Profinet EthernetlP EthernetlP EthercAT EthercAT Rotor Sensor Facoder Y Encoder Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs 8 8 Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 8 Brake Resistor Outputs 123x83x25mm 123x83x25mm <	Cont Amps/ch	20 (40)	20 (40)	
STO	Max Voltage	60	60	
Communication RS232 Y Y RS485 Y Y CANbus Y Y Ethernet Profinet EthernetIP Ether CAT Ether CAT Rotor Sensor Encoder Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs 8 8 Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP40 IP40	Power Connections	Screw Terminal	Molex Megafit	
RS232	STO	Υ		
RS485 Y CANbus Y Ethernet Profinet EthernetIP EtherCAT Rotor Sensor Encoder Y Hall Y Sin/Cos Y SSI Single-turn Y SSI Multi-turn Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs Max Analog Inputs 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 Max Digital Outputs 4 PWM Brake Outputs Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Communication			
CANbus Y Y Ethernet Profinet EthernetIP EtherCAT EtherCAT Rotor Sensor Y Y Encoder Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs 8 8 Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 2 Brake Resistor Outputs 1/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	RS232	Υ	Υ	
Ethernet Profinet EthernetIP EtherCAT Rotor Sensor Y Encoder Y Hall Y Sin/Cos Y SSI Single-turn Y SSI Multi-turn Y Resolver Y Sensor Connector Molex Microfit Input/Outputs Molex Microfit Max Analog Inputs 8 Max Digital Inputs 10 Max Pulse Inputs 8 Max Digital Outputs 4 PWM Brake Outputs 2 Brake Resistor Outputs 1/O Connector Dimensions 123x83x25mm Cooling Conduction IP Rating IP40	RS485	Υ		
Profinet EthernetIP EtherCAT Rotor Sensor Encoder Y Y Y Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 4 PWM Brake Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating	CANbus	Υ	Υ	
EthernetIP EtherCAT Rotor Sensor Y Encoder Y Hall Y Sin/Cos Y SSI Single-turn Y SSI Multi-turn Y Resolver Y Sensor Connector Molex Microfit Input/Outputs Molex Microfit Max Analog Inputs 8 Max Digital Inputs 10 Max Pulse Inputs 8 Max Digital Outputs 4 PWM Brake Outputs 2 Brake Resistor Outputs 1/O Connector Dimensions 123x83x25mm Cooling Conduction IP Rating IP40	Ethernet			
EtherCAT Rotor Sensor Fincoder Y Y Y Y Y Sin/Cos Y Y Y Y Sin/Cos Y Y Y Y Y Y SSI Single-turn Y Y Y Y Y Y Y Y Y	Profinet			
Rotor Sensor Encoder Y Y Y Y Y Sin/Cos Y Y Y Y SIn/Cos Y Y Y Y Y Y Y Y SI Single-turn Y Y Y Y Y Y Y Y Y	EthernetIP			
Encoder	EtherCAT			
Hall Y Y Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm Cooling Conduction IP Rating IP40 IP40	Rotor Sensor			
Sin/Cos Y Y SSI Single-turn Y Y SSI Multi-turn Y Y Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs Max Analog Inputs 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 4 4 PWM Brake Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Encoder	Υ	Υ	
SSI Single-turn SSI Multi-turn Resolver Sensor Connector Molex Microfit Input/Outputs Max Analog Inputs Max Digital Inputs Max Pulse Inputs Max Digital Outputs PWM Brake Outputs Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions Cooling Conduction IP Rating V Y Y Y Y Y Y Y Y Y Y Y Y	Hall	Υ	Υ	
SSI Multi-turn Resolver Sensor Connector Molex Microfit Molex Microfit Input/Outputs Max Analog Inputs Max Digital Inputs Max Pulse Inputs Max Digital Outputs Max Digital Outputs Frake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm Cooling Conduction IP Rating PWM Brake Outputs Conduction IP40	Sin/Cos	Υ	Υ	
Resolver Sensor Connector Input/Outputs Max Analog Inputs Max Digital Inputs Max Pulse Inputs Max Digital Outputs Max Digital Outputs Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm Cooling Conduction IP Rating IMOLEX Microfit Molex Microfit Mechanical 8 8 8 4 4 4 4 PWM Brake Outputs 2 Brake Resistor Outputs 123x83x25mm Conduction Conduction IP40	SSI Single-turn	Υ	Υ	
Sensor Connector Molex Microfit Molex Microfit Input/Outputs Max Analog Inputs 8 8 8 Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	SSI Multi-turn	Υ	Υ	
Input/Outputs 8 8 Max Analog Inputs 10 10 Max Digital Inputs 8 8 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Resolver			
Max Analog Inputs 8 Max Digital Inputs 10 Max Pulse Inputs 8 Max Digital Outputs 4 PWM Brake Outputs 2 Brake Resistor Outputs Molex Nanofit I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Sensor Connector	Molex Microfit	Molex Microfit	
Max Digital Inputs 10 10 Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Input/Outputs			
Max Pulse Inputs 8 8 Max Digital Outputs 4 4 PWM Brake Outputs 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Max Analog Inputs	8	8	
Max Digital Outputs 4 4 PWM Brake Outputs 2 Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	Max Digital Inputs	10	10	
PWM Brake Outputs Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm Cooling Conduction IP Rating IP40 IP40	Max Pulse Inputs	8	8	
Brake Resistor Outputs I/O Connector DSub25 Molex Nanofit Mechanical Dimensions 123x83x25mm Cooling Conduction IP Rating DSub25 Molex Nanofit Molex Nanofit Molex Nanofit Molex Nanofit IP40 IP40	Max Digital Outputs	4	4	
I/O ConnectorDSub25Molex NanofitMechanicalDimensions123x83x25mm123x83x25mmCoolingConductionConductionIP RatingIP40IP40			2	
Mechanical123x83x25mm123x83x25mmCoolingConductionConductionIP RatingIP40IP40	Brake Resistor Outputs			
Dimensions 123x83x25mm 123x83x25mm Cooling Conduction Conduction IP Rating IP40 IP40	I/O Connector	DSub25	Molex Nanofit	
Cooling Conduction Conduction IP Rating IP40 IP40	Mechanical			
IP Rating IP40 IP40	Dimensions	123x83x25mm	123x83x25mm	
	Cooling	Conduction	Conduction	
unini volotog og	IP Rating	IP40	IP40	
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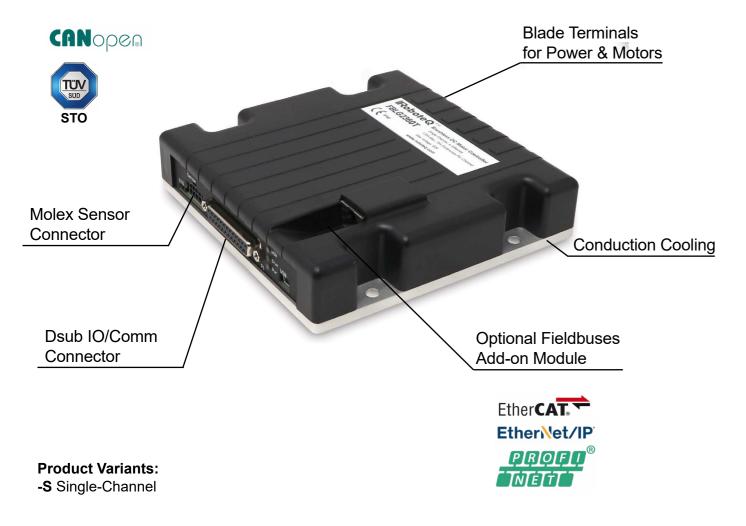
SBLG2360T

SBLMG2360T



F-Series Mid-Power Dual-Channel

FBLG2360T 2x60A / 1x120A

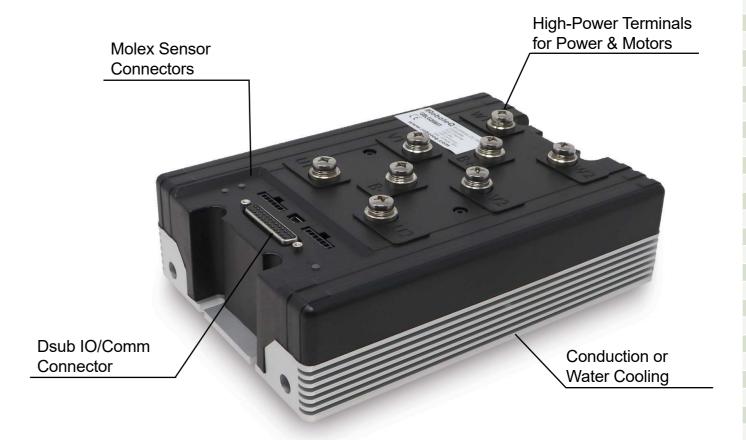


	FBLG2360T	
Power		
Number of Channels	2 (1)	
Max Amps/ch	60 (120)	
Cont Amps/ch	40 (90)	
Max Voltage	60	
Power Connections	Fast-on	
STO	Υ	
Communication		
RS232	Υ	
RS485	Υ	
CANbus	Υ	
Ethernet	-E -P versions	
Profinet	-P versions	
EthernetIP	-I versions	
EtherCAT	-C versions	
Rotor Sensor		
Encoder	Υ	
Hall	Υ	
Sin/Cos	Υ	
SSI Single-turn	Υ	
SSI Multi-turn	Υ	
Resolver	Υ	
Sensor Connector	Molex Microfit	
Input/Outputs		
Max Analog Inputs	10	
Max Digital Inputs	8	
Max Pulse Inputs	8	
Max Digital Outputs	4	
PWM Brake Outputs		
Brake Resistor Outputs		
I/O Connector	DSub25	
Mechanical		
Dimensions 140x140x25mm		
Cooling	Conduction	
IP Rating	IP40	

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G-Series Compact High-Power Dual-Channel

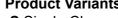
GBLG2660T 2x180A / 1x360A



Product Variants: -S Single-Channel











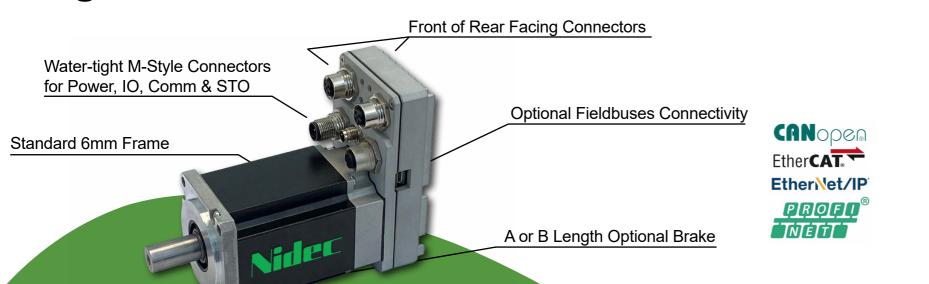




IIRoboG4[™]

RoboG4

iLD Integrated Motors + Drives



Product Variants: 060 iL A 30 5 - S T C S

Motor Frame	060
Motor Type	iL (i – Integrated), (L – 48VDC)
Motor Length	A or B
Motor Shaft Speed	30 rpm
Motor Brake	0,5 (with or without)
Controller	S (GSBL)
STO/PWRC	T (STO), P (Power Control)
Network	
	I (Ethernet IP), E (EtherCat)
Encoder	S (Single Turn)

iLD60S

AGV Kits



The kits contain the following: a pair of motors with gearboxes and wheels, a preset and tuned dual-channel drive, and cable assemblies. Kits are available in three sizes of motors and drives for robots weighing up to 500, 1000 and 2000kg.

	AGV060B	AGV089A	AGV142A
Max Robot Weight	500kg	1000kg	2000kg
Motor Frame	60mm	89mm	142mm
Max Motor RPM	3000	3000	2000
Gear Ratio	9:1	9:1	9:1
Wheel Diameter	156mm	156mm	202mm
Brake	No Brake: 01 Suffix w/ Brake: 02 Suffix	No Brake: 01 Suffix w/ Brake: 02 Suffix	No Brake: 01 Suffix w/ Brake: 02 Suffix
Drive Model	SBLG2360T	FBLG2360T	GBLG2660T

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Dual-Channel drives are simpler, cheaper, and easier to integrate and maintain. Motors are coordinated within the drive, resulting in superior and safer drive characteristics compared to two single-channel drives.

Complementary Products



Safety Electric Brake Switch

The SB\$1360 is a Functional Safety device that uses redundant solid-state switches for strong electrical braking -stopping the motor up to 10 times faster compared to STO alone.



Shunt Regulators

The SR5K is a protection device for dissipating the regenerative energy when braking. It instantly applies a two-level resistive load in overvoltage conditions to absorb up to 5 kilowatt of excess



Magnetic Charge Contacts

Robopad charge contacts are a two-part system (base + extendable collector) that uses magnetic force to secure a high current charging solution for mobile robots and AGVs.







Magnetic Track Following Sensors

The MGS1600 sensor reports the position of a magnetic field with 1mm accuracy. It is intended for Automatic Guidance, using adhesive magnetic tape to form a guide on the floor.







Founded in 2005, Roboteg established itself as a leader in the field of servo drives, primarily in the fast-growing mobile robot market. In 2020, Roboteq was acquired by Nidec Corporation, the world's most comprehensive maker of electric motors. Roboteg's drive expertise is now augmented by Nidec's global resources. Our growing team of engineers and scientists integrate

leading-edge technologies from Nidec's corporate advanced research centers. Investments in design, test and validation tools are combined with rigorous methodologies that further advance the quality and reliability of our drives.

With factories all around the globe, we can satisfy the largest orders at reasonable costs.

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"Excellent Product"

"I've worked with a lot of motor controllers and I have to say that so far these are the BEST I've worked with. Great job on the design and the software." T.K. - USA

"Solid Documentation"

"I've been in product development and engineering for guite a few years and I feel this is the best manual I've seen in that time. It's complete, relevant and explanatory. Well done!"

B.B. - Netherlands

"Beyond Product Support"

"The Roboteq team has been with us all along our design efforts, helping with communication to our PLC and advising us on how to best construct our mechanical chassis in order to achieve accurate and steady track following. Thank you!"

R.B. - Canada

"Integration Really is a Snap"

"Roboteg's sensor, motor controller and software really do come together easily as advertised. Following their documentation and using their sample script was all we needed to make our robot move within hours. Impressive!"

A.G. - Spain

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