# **O3** LINEAR ACTUATORS WITH INTEGRATED REDUCTION AND CUBIC GEARBOX

FM Series: Steel tube AM Series: Aluminum tube



# "SUSTAINABILITY IS INDUSTRIALISED ECOLOGY." David garcía

**HOME-THERME** 

NIASA ACTUATORS IN THE TONOPAH THERMO-SOLAR PLANT, NEVADA, USA.





## WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **INTRODUCTION**

NIASA FM/AM Series electro-mechanical actuators combine the sleeve and stem system of the F/A Series linear actuators with the gearbox of the screw jacks, thus obtaining the most interesting features of both types of product.

This way, the FM/AM Series electro-mechanical actuators become the optimal technical solution for applications that require the movement specifications of a screw jack, with the additional advantage of being able to work under the most demanding environmental conditions.

Their main advantages against other systems, such as pneumatic or hydraulic cylinders, are the following:

- ... Greater movement and positioning precision.
- ... Greater safety, due to its irreversibility in many configurations (ask NIASA) and/or the incorporation of different braking devices.
- ... Superior energy efficiency, as their parts offer high/very high performance, especially with the ball screws, low transmission ratios and high speeds.
- ... Easier and faster assembly, since hydraulic or pneumatic groups are not required, just an electric motor on the unit itself.
- ... Greater reliability and duration, and less maintenance, due to the mechanical robustness and construction simplicity.
- ... Modular design and the possibility to operate in multiple positions.
- ... Easier to obtain synchronized advance movements of several actuators, including under different loads.
- ... Lower size for the same load capacity.

... ...

The screw supports also characterized for offering an extensive range of:

- ... Axial load capacities, from 5 kN up to 250 kN.
- ... Advance speeds; depending on the screw pitch and the gearbox, two possible reductions are offered depending on the size of the actuator, from 4:1 to 40:1.
- ... Trapezoidal and ball screws, depending on the performance required, precision of movement and positioning, etc.
- ... Fastening accessories and elements, for optimal adaptation to the most varied systems that may be designed.
- ... Control and safety systems (mechanical/inductive limit switches, absolute/incremental encoders, etc.).
- ... Materials and surface coverings, depending on the environmental conditions in which the unit will be installed.
- ... Two types of external sleeve for the stem:
  - · Steel round tube.
  - · Aluminum extrusion profile (magnetic sensors, antirotation system).
- ... ..

Please do not hesitate to contact NIASA if you require FM/AM actuators (and their drive mechanisms) with specifications other than those covered in this chapter. The NIASA technical department will specifically develop the special units that best meet your requirements.



WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **APPLICATIONS**

## **PRESS TYPE SYSTEM**

Three FM3 Series actuators made up of a three-phase motor drive system, MK Series drive union flange, with MK Series drive, transmission between equipment using MK series coupling, BP Series fastening flanges on the stem and PR Series protector on the worm shaft.

## THREE SHAFT SCREW JACK SYSTEM

Three FM3 series actuators made up of a double-shaft, three-phase drive system, transmission between units with EZ series joint shafts, FCI series inductive sensor with a position encoding system underneath the gearbox, bevel gearbox with encoder adapted and GIR series ball with joint fastening on the stem.

## CONVEYOR BELT ELEVATION SYSTEM

Two FJ1 Series actuators made up of a three-phase drive system with brake, MK Series drive union flange, transmission between units with EZ Series joint shafts, support structure with protection for the transmission shaft, GIR series ball joint on the stem and HFM Series gearbox fastening.

## ELEVATION SYSTEM WITH INTEGRATED MAGNETIC SENSOR.

Two AM2 Series actuators made up of a three-phase motor drive system, drive union flange, transmission between units with EZ Series joint shafts, exterior aluminum tube with anti-turning system and an FCG Series integrated magnetic sensor, tilt fastening on the BA Series tube, GKB Series ball joint fastening on the stem.



WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

**SIZES** 

There are trapezoidal and ball screw options on all the sizes (see chapter on screws for further information), as well as normal speed (S) and slow speed (H) gearboxes.

	M1	M2	M3
Up to	5 kN	10 kN	25 kN
<b>F</b> Steel exterior tube	page 122	page 123	page 124
A Aluminum exterior tube With anti-rotation on the stem (optional)	1	Ĺ	Ĺ
With magnetic sensor integrated on the aluminum tube (optional)	page 122	page 123	page 124

In addition to the standard range of linear actuators, NIASA can specifically develop the unit that best meets your application requirements. Contact NIASA.

IMPORTANT All the technical data included in this chapter correspond to the configuration with steel tube and to the aluminum tube configuration.

For further information about the latter, please contact the NIASA technical department.







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## MASA

# **LINEAR ACTUATORS**

WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

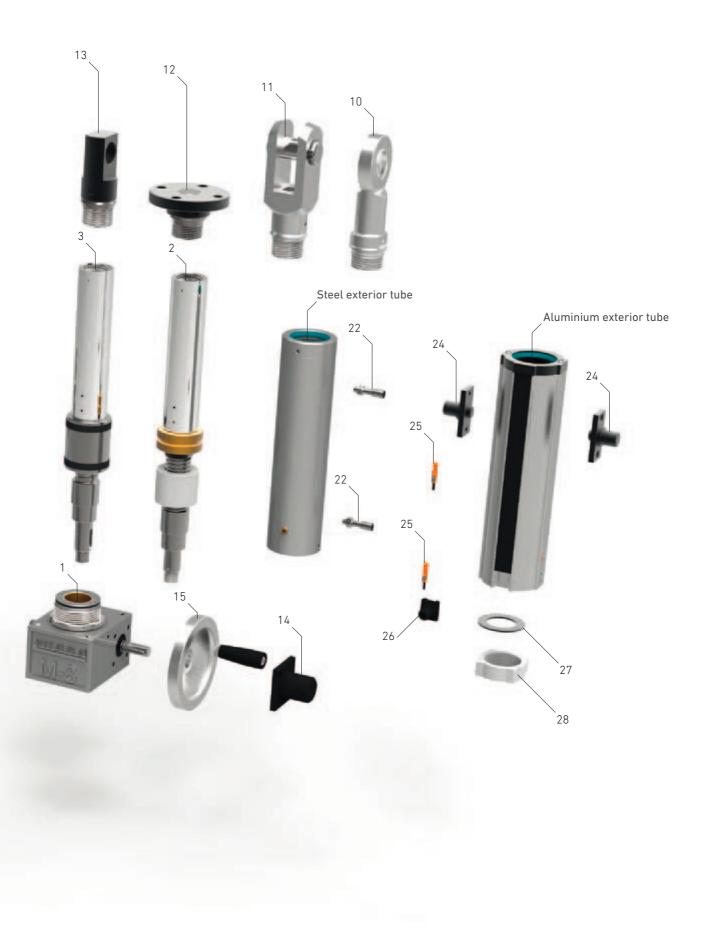
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## **GENERAL PRODUCT OVERVIEW**

	Name	Page
01	M SERIES GEARBOX	118
02	Screw + Trapezoidal nut + Stem	122
03	Screw + Ball nut + Stem	122
04	HFM ball joint	270
05	LCM mounting feet	266
06	Flange with ZKM bolts	267
07	Flanges with ZKH bearings	268
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09	SB tilt supports	276
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17	EK coupling	284
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20	BB flanges with bolts for steel tube	272
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22	FCI inductive limit switch	307

24	BA flanges with bearings for aluminum tube	274
25	FCG magnetic limit switch	308
26	Connection sensor input adapter	308
27	Position sensor magnet	308
28	Anti-rotation system	

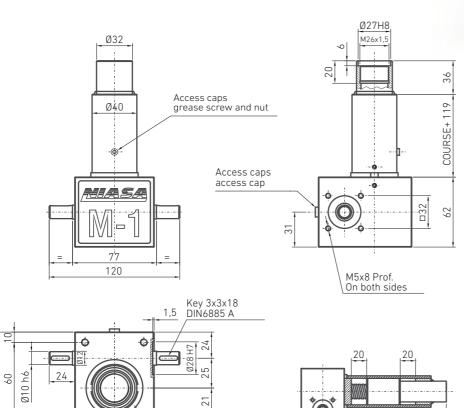






# FM1/AM1 LINEAR ACTUATOR





SAFETY	MARGIN

36

Diameter and step screw	Maximum axial strength	Redu	16:1 1.00 0.	revol.		rmance %)		ue, M <sub>D</sub> (Nm) load to move in	torque,	t-up M <sub>o</sub> (Nm)	Weight stroke 0 (kg)	Approx. weight each 100 mm of	
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(rg)	stroke (kg)
Tr 16x4	5	4:1	16:1	1.00	0.25	35	27	(0,46xF)+0.17	(0,15xF)+0.08	0.80xF	0.34xF	1.8	0.5
KGS 1605	5	4:1	16:1	1.25	0.31	71	56	(0.28xF)+0.14	(0.09xF)+0.08	0.39xF	0.16xF	1.8	0.5

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... Power required:  $P_{p}$  (kW) = 0,157x  $M_{p}$  (Nm).

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52

72

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M8x13 Prof.

On both sides

... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130). Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).

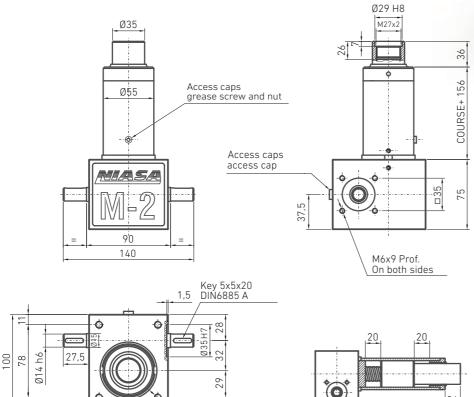


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## **FM2/AM2 LINEAR ACTUATOR** UP TO 10 kN THE KGS BALLS





SAFETY MARGIN

36

Diameter and step	Maximum axial	Redu	uction		ance 'revol.		mance	Drive torqu	ue M <sub>p</sub> (Nm)		o torque, Nm)	Weight	Approx. weight	
screw	strength			inp	input) (%)			F (kN),		stroke 0 (kg)	each 100 mm of			
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(itg)	stroke (kg)	
Tr 24x5	10	4:1	16:1	1.25	0.31	0.31	0.25	(0.64xF)+0.35	(0.20xF)+0.17	1.11xF	0.43xF	4.6	1	
KGS 2005	10	4:1	16:1	1.25	0.31	0.72	0.58	(0.28xF)+0.33	(0.09xF)+0.17	0.39xF	0.15xF	4.6	1	
KGS 2020	7.5	4:1	16:1	5.00	1.25	0.72	0.58	(1.10xF)+0.33	(0.35xF)+0.17	1.55xF	0.6xF	4.6	1	

... Power required:  $P_{D}$  (kW) = 0,157x  $M_{D}$  (Nm).

0

63

85

M8x15 Prof.

On both sides

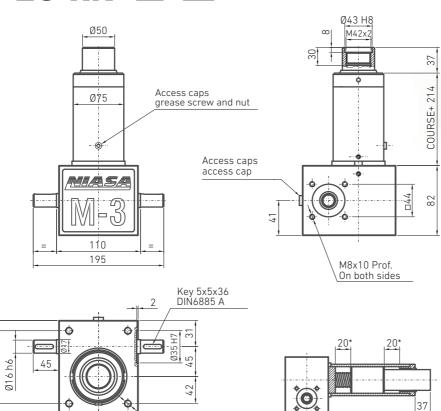
... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130).

... Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).





# FM3/AM3 LINEAR ACTUATOR



M10x15 Prof.

On both sides





Diameter and step	ep axial Reduction v strength (kN)		uction	Advance on (mm/revol. input)		revol.		Drive torque $M_{\rm p}$ (Nm)		$\begin{array}{c} \text{Start-up torque,} \\ \text{M}_{\text{o}}\left(\text{Nm}\right) \end{array}$		Weight	Approx. weight	
screw								F (kN), load to move in dynamic				stroke 0 (kg)	each 100 mm of	
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(Ng)	stroke (kg)	
Tr 36x6	25	6:1	24:1	1.00	0.25	0.28	0.22	(0.58xF)+0.57	(0.18xF)+0.31	1.04xF	0.4xF	12	2.1	
KGS 3205	20	6:1	24:1	0.83	0.21	0.73	0.58	(0.18xF)+0.52	(0.06xF)+0.29	0.26xF	0.11xF	12	2.1	
KGS 3210	25	6:1	24:1	1.67	0.42	0.73	0.58	(0.36xF)+0.52	(0.12xF)+0.29	0.52xF	0.21xF	12	2.1	
KGS 3220	20	6:1	24:1	3.33	0.83	0.73	0.58	(0.73xF)+0.52	(0.23xF)+0.29	1.03xF	0.42xF	12	2.1	
KGS 3240	10	6:1	24:1	6.67	1.67	0.73	0.58	(1.46xF)+0.52	(0.46xF)+0.29	2.07xF	0.84xF	12	2.1	

... Power required:  $P_{D}$  (kW) = 0,157x  $M_{D}$  (Nm).

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... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130).

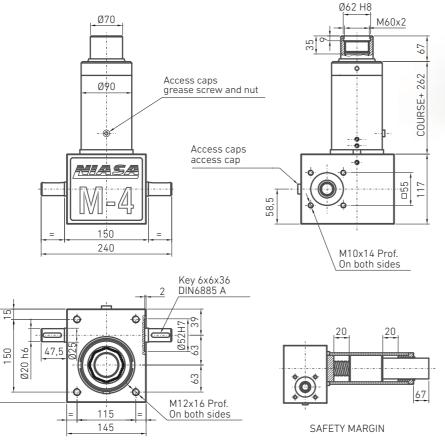
... Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).



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# FM4/AM4 LINEAR ACTUATOR





Diameter and step screw	Maximum axial strength	Redu	uction	(mm/	ance 'revol. out)		rmance %)	Drive torqu F (kN),		o torque, Nm)	Weight stroke 0 (kg)	Approx. weight each 100 mm of	
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(kg)	stroke (kg)
Tr 45x7	50	7:1	28:1	1.00	0.25	0.26	0.21	(0.61xF)+0.97	(0.19xF)+0.57	1.18xF	0.44xF	27.3	3.3
KGS 4010	42	7:1	28:1	1.43	0.36	0.73	0.60	(0.31xF)+0.93	(0.09xF)+0.56	0.45xF	0.18xF	27.3	3.3
KGS 4020	37	7:1	28:1	2.86	0.71	0.73	0.60	(0.62xF)+0.93	(0.19xF)+0.56	0.9xF	0.36xF	27.3	3.3
KGS 4040	35	7:1	28:1	5.71	1.43	0.73	0.60	(1.25xF)+0.93	(0.38xF)+0.56	1.8xF	0.72xF	27.3	3.3

... Power required:  $P_{D}$  (kW) = 0,157x  $M_{D}$  (Nm).

... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130).

... Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).

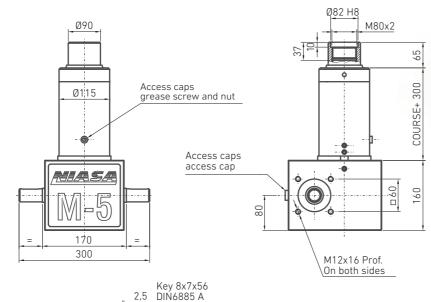


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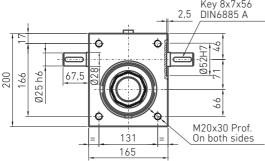


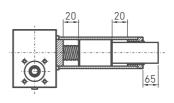


The capacity indicated corresponds to the basic configuration. There is a possibility for higher capacities on request.









SAFETY MARGIN

Diameter and step screw	Maximum axial strength	Redu	uction	(mm/	ance 'revol. out)	Performance (%)		Drive torqu F (kN),		o torque, Nm)	Weight stroke 0 (kg)	Approx. weight each 100 mm of	
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(rg)	stroke (kg)
Tr 50x8	100	9:1	36:1	0.89	0.22	0.27	0.21	(0.53xF)+1.91	(0.17xF)+1.08	0.98xF	0.39xF	45.2	4.9
KGS 5010	65	9:1	36:1	1.11	0.28	0.73	0.58	(0.24xF)+1.87	(0.08xF)+1.07	0.36xF	0.15xF	45.2	4.9

... Power required:  $P_{D}$  (kW) = 0,157x  $M_{D}$  (Nm).

... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130).

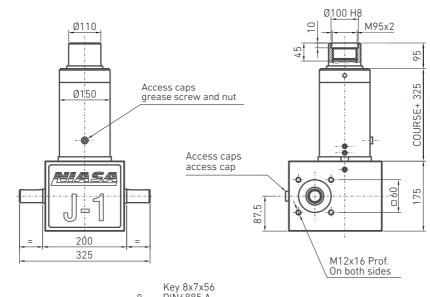
... Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).







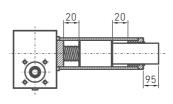
The capacity indicated corresponds to the basic configuration. There is a possibility for higher capacities on request.







								8	Key DIN6	8x7x56 885 A
7	20						5		101	
210	170	Ø25 h6	<b>C</b>	028	ſ				H700	
		Ø25			Ć	Ŋ	2		70	
1	1			=	15	5	=		24x40 i both	Prof. sides
				-	19	25	-			



SAFETY MARGIN

Diameter and step screw	Maximum axial strength	Redu	uction	(mm/	ance /revol. out)	Performance (%)			Drive torque, M <sub>p</sub> (Nm) F (kN), load to move in			Weight stroke 0 (kg)	Approx. weight each 100 mm of
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(kg)	stroke (kg)
Tr 70x10	150	9:1	36:1	1.11	0.28	0.24	0.18	(0.73xF)+2.3	(0.24xF)+1.21	1.31xF	0.49xF	84.8	9
KGS 6310	65	9:1	36:1	1.11	0.28	0.73	0.55	(0.24xF)+1.97	(0.08xF)+1.19	0.33xF	0.14xF	86.8	9

... Power required:  $P_{D}$  (kW) = 0,157x  $M_{D}$  (Nm).

... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130).

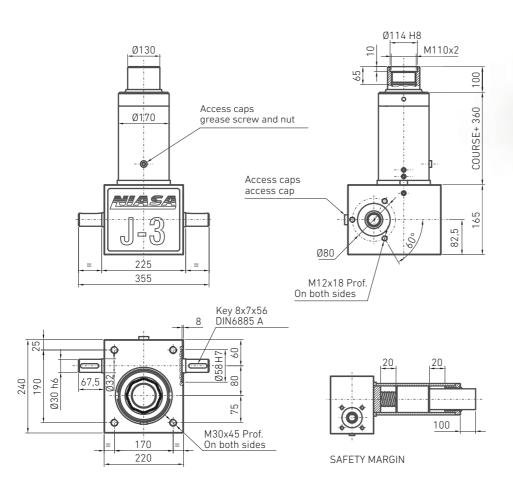
... Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).







Contact versions with ball screw.





Diameter	ximum Reduction		Advance ction (mm/revol.		Performance		Drive torque, M <sub>D</sub> (Nm)		Start-up torque, M <sub>0</sub> (Nm)		Weight	Approx. weight	
screw	screw strength		input)				F (kN), load to move in dynamic				stroke 0 (kg)	each 100 mm of	
(mm)	(kN)	S	Н	S	Н	S	Н	S	Н	S	Н	(	stroke (kg)
Tr 80x10	250	10:1	40:1	1.00	0.25	0.22	0.19	(0.73xF)+2.81	(0.21xF)+1.95	1.18xF	0.4xF	100	14

... Power required:  $\rm P_{_{D}}$  (kW) = 0,157x  $\rm M_{_{N}}$  (Nm).

... All the data in the table correspond to an input speed of 1,500 rpm. For other speeds, please see the calculation chapter (page 130).

... Ensure that the application's dynamic load does not exceed the critical values indicated, in order to avoid overheating of the unit and buckling and resonance. See calculations chapter (page 130).



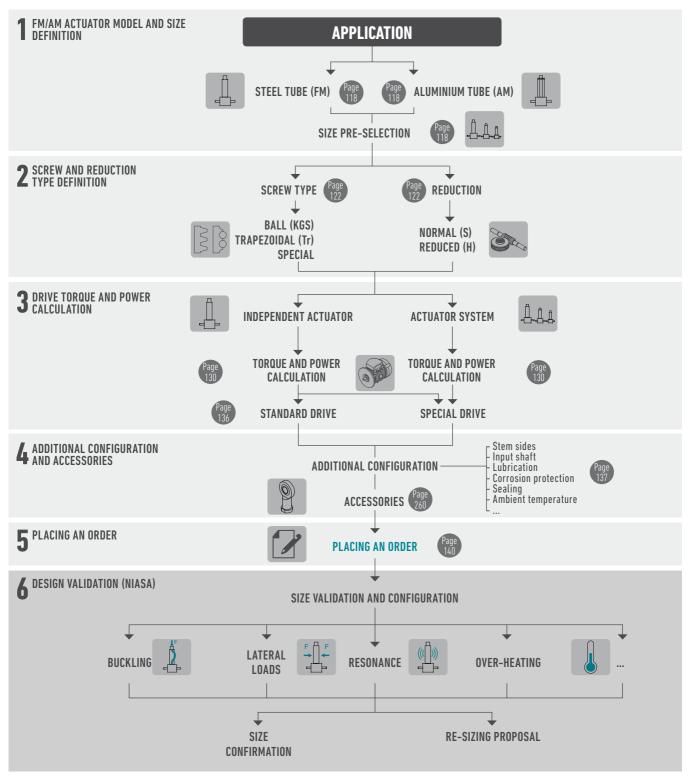


# **LINEAR ACTUATORS** WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

To select the correct FM/AM Series linear actuator, please follow this flow diagram.

If you would like to know the expected service life of a unit for your application, please send the relevant data to the NIASA service department.

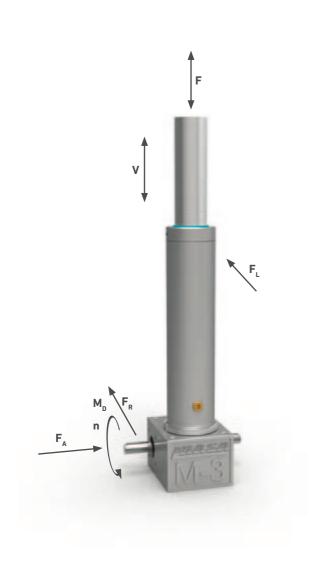


WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

## FORCE AND TORQUE ACTING ON AN **FM /AM SERIES ACTUATOR**

- Load to move at traction and/or compression. F
- Lateral load on the stem. F
- v Stem travel speed.
- F, Axial load on the input shaft.
- F<sub>n</sub> Radial load on the input shaft.
- M Torque on the input shaft.
- n Speed on the input shaft.



## **TORQUE AND POWER OF A LINEAR ACTUATOR INDEPENDENT FM/AM SERIES**

After pre-selecting the suitable FM/AM Series linear actuator for the application, select the drive motor following the steps below:

## **1. DRIVE TORQUE**

$$M_{p}(Nm) = \frac{F \times P}{2 \times \pi \times 0.9 \times \eta_{pg} \times \eta_{ps} \times i} + M_{i}$$

- M<sub>n</sub> Drive torque (kN)
- **F** Load to move in dynamic (kN)
- P Screw pitch (mm)
- M. Idle torque (Nm)
- i Actuator reduction
- 0.9 Cylinder dynamic efficiency
- **n**<sub>ng</sub> Gearbox dynamic efficiency
- **n**<sub>ps</sub> Screw dynamic efficiency

### 2. POWER REQUIRED

$$\mathbf{P}_{\mathbf{p}} (\mathbf{kW}) = \frac{\mathsf{M}_{\mathbf{p}} \mathbf{x} \mathsf{n}}{9550}$$

M **n** Screw jack input speed (rpm)

#### IMPORTANT

- ... In general, it is advisable to multiply the power value calculated for a safety coefficient of 1.3 to 2; the smaller the installation the higher the coefficient
- ... When the load to move is lower than 10% of the elevator's nominal load, consider that value as the load to move.

#### **3. START-UP TORQUE**

For loads between 25% and 100% of the actuator's nominal value, calculate the start-up torque with this formula:

$$M_{0}(Nm) = \frac{F \times P}{2 \times \pi \times 0.9 \times \eta_{sa} \times i}$$

 $\mathbf{\eta}_{\mathbf{sA}}$  Actuator static efficiency (gearbox + screw)

#### IMPORTANT

... For loads under 25% of the actuator's nominal value, select the start-up torque by multiplying the drive torque by 2.

#### $\eta_{_{DG}}$ Gearbox dynamic efficiency

#### S gearbox version (normal speed) FM1/ FM2/ FM3/ input FM4/ FM5 FJ1 FJ3 rpm AM1 AM2 AM3 AM4 3,000 0.91 0.90 0.92 Non-standard 1,500 0.88 0.89 0.90 0.90 0.90 0.90 0.90 1000 0.87 0.88 0.88 0.88 0.87 0.89 0.89 0.85 0.87 0.87 0.88 0.89 750 0.87 0.86 500 0.84 0.85 0.85 0.85 0.84 0.87 0.88 0.79 0.79 0.79 0.79 0.78 0.81 0.84 100

#### H gearbox version (slow speed)

input rpm	FM1/ AM1	FM2/ AM2	FM3/ AM3	FM4/ AM4	FM5	FJ1	FJ3
3,000	0.75	0.77	0.76		Non-st	andard	
1,500	0.69	0.71	0.71	0.74	0.72	0.68	0.77
1000	0.67	0.69	0.68	0.69	0.67	0.67	0.76
750	0.64	0.66	0.67	0.68	0.65	0.65	0.75
500	0.61	0.64	0.63	0.64	0.62	0.64	0.74
100	0.54	0.56	0.54	0.55	0.53	0.55	0.66

## $\eta_{\text{DS}}$ Screw dynamic efficiency

Trapezoidal screw (Tr)								
16x4	24x5	36x6	45x7	50x8	70x10	80x10		
0.44	0.39	0.34	0.32	0.33	0.30	0.27		
	Ball screw (KGS)							
0.9 (for all sizes)								

#### M, Idle Torque

S gearbox version (normal speed)

	FM1/ AM1	FM2/ AM2	FM3/ AM3	FM4/ AM4	FM5	FJ1	FJ3
Trapezoidal	0.17	0.35	0.57	0.97	1.91	2.03	2.81
Balls	0.14	0.33	0.52	0.93	1.87	1.97	2.75

H gearbox version (slow speed)
--------------------------------

	FM1/ AM1	FM2/ AM2	FM3/ AM3	FM4/ AM4	FM5	FJ1	FJ3
Trapezoidal	0.08	0.17	0.31	0.57	1.08	1.21	1.95
Balls	0.08	0.17	0.29	0.56	1.07	1.19	1.94

### $\eta_{\text{sA}}$ Actuator static efficiency

S gearbox version (normal speed)

	FM1/ AM1	FM2/ AM2	FM3/ AM3	FM4/ AM4	FM5	FJ1	FJ3
Trapezoidal	0.22	0.20	0.17	0.15	0.16	0.15	0.15
Balls	0.57	0.57	0.57	0.56	0.55	0.59	0.64

H gearbox version (slow speed)								
	FM1/ AM1	FM2/ AM2	FM3/ AM3	FM4/ AM4	FM5	FJ1	FJ3	
Trapezoidal	0.13	0.13	0.11	0.10	0.10	0.10	0.11	
Balls	0.35	0.37	0.35	0.35	0.32	0.36	0.45	

#### IMPORTANT

... The values indicated in the tables correspond to the lubrication conditions established by NIASA, for gearbox and screw, and will be reached after a small period of operation.

... In the case of low temperatures, these can be reduced considerably.

WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

# DESIGNING INSTALLATIONS WITH FM/AM SERIES LINEAR ACTUATORS

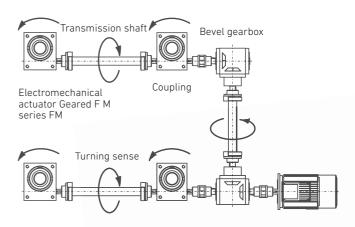
For the application of FM/AM Series linear actuators in installations with several units, the following criteria must be taken into account:

**1.** Define the number, position and orientation of the equipment.

- **2.** Select the drag components (couplings, transmission shafts, supports, bevel gearboxes, motors, etc.) taking the following recommendations into account:
  - ... Ensure that the total load is distributed uniformly between all the installation's actuators.
  - ... The lowest possible number of transmission parts is recommended.
  - ... The transmission shafts should be as short as possible.
  - ... Try to protect the overall installation with a safety torque limiter.
- **3.** If a problem arises during the design of the installation in defining the turning sense of the different elements, it is advisable to apply the following method:
  - ... Indicate the orientation of the actuator elements.
  - ... Mark the screw turning sense on each actuator to "lift".
  - ... Show the position of the bevel gearboxes and the transmission shafts in a diagram.

#### Example:

Elevation system with four FM linear actuators and two bevel gearboxes.







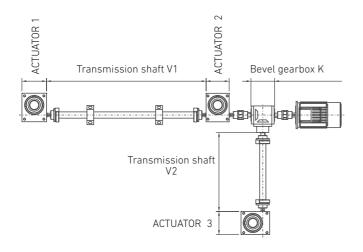
WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

## DRIVE TORQUE OF AN FM/AM SERIES LINEAR ACTUATOR SYSTEM

The drive torque of a system made up of several FM/AM Series linear actuators connected to each other depends on the torque required for the individual drive of each one and the efficiency of the transmission parts that connect them.

#### Example:



#### **1. SYSTEM DRIVE TORQUE**

$$M_{DS} (Nm) = \frac{M_{D1}}{\eta_{V1}} + M_{D2} + \left(\frac{M_{D3}}{\eta_{V2}} \times \frac{1}{\eta_{K}}\right)$$

 $\begin{array}{ll} \textbf{M}_{\text{p1}} / \textbf{M}_{\text{p2}} / \textbf{M}_{\text{p3}} & \text{Actuator drive torque 1 / 2 / 3 (Nm)} \\ \textbf{\eta}_{\text{v1}} / \textbf{\eta}_{\text{v2}} & \text{Gearbox efficiency V1/V2} \\ & (0.90 - 0.95 \text{ approx.}) \\ \textbf{\eta}_{\text{K}} & \text{Bevel gearbox efficiency (0.90 approx.)} \end{array}$ 

#### IMPORTANT

- ... In general, it is advisable to multiply the value calculated for a safety coefficient of 1.3 to 1.5; or for small installations, a factor of 2.
- ... When the load to move is lower than 10% of the elevator's nominal load, consider that value for the previous calculations.

To help the calculation, some frequent arrangements are shown for those for which the system's drive torque can be calculated approximately using the following formula.

It is assumed that the load distribution is uniform between all the units and that they are all the same size.

### $M_{ps} (Nm) = M_{p} + f_{s}$

M<sub>n</sub> Independent elevator drive torque

 $f_s$  Factor, according to system (see figures next page)

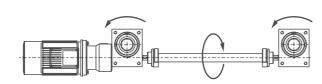
## 2.SYSTEM START-UP TORQUE

For loads by screw jack between 25% and 100% of the screw jack's nominal value, calculate the start-up torque with this formula:

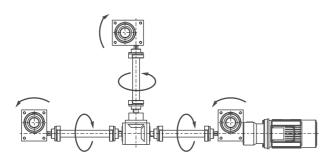
$$M_{_{DS}}(Nm) = \frac{M_{_{DS}}}{\eta_{_{SA}}}$$

#### IMPORTANT

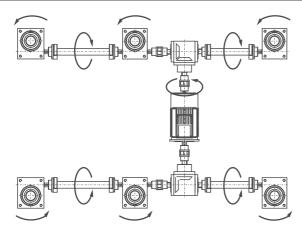
... For loads by elevator lower than 25% of its nominal value, multiply the system drive torque by 2.



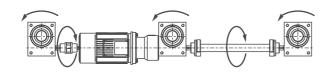
f<sub>s</sub> = 3.34



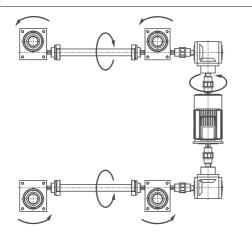
f<sub>s</sub> = 6.8



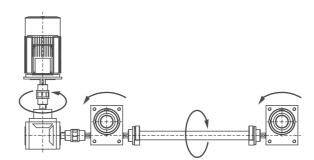
f<sub>s</sub> = 3.1



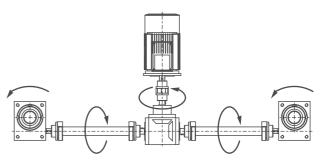
 $f_{s} = 4.4$ 



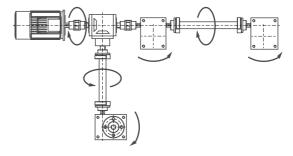




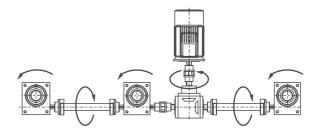
f<sub>s</sub> = 2.25



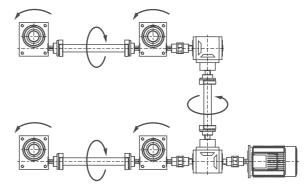
f<sub>s</sub> = 3.27



f<sub>s</sub> = 3.35



f<sub>s</sub> = 4.6



WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

## **STANDARD DRIVE**

The standard drive of the FM/AM Series linear actuators is made using Ac motors.

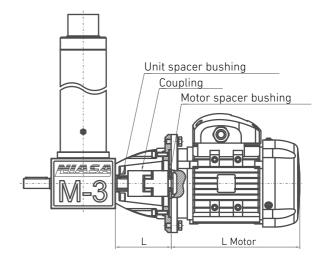
The following table shows the powers available for each actuator size and the type of flange on the motor, in addition to the length of its fastening flange to the gearbox. For another size or different type of drive, please contact NIASA. NIASA can supply alternating or stepper motors with sensors of any type, etc.

				1										1						
										мото	R GRC	UP			1					
		5	6	6	3	7	71	8	0	9	0	1(	00	112	13	32	16	0	18	30
	Motor flange	Motor flange			POWER (kW)															
	А		В	А	В	А	В	А	В	А	В	А	В	А	А	В	А	В	А	В
		0.06	0.09	0.12	0.18	0.25	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	22
	L	5	7	6	0	6	57	i												
FM1 / AM1	Motor flange	B	B14 B14		В	14														
	L		63			7	'0	8	3											
FM2 / AM2	Motor flange		B14		В	14	В	14												
	L				9	21	1	01	1	13		123								
FM3 / AM3	Motor flange					E	35	В	14	B14 B14										
FM4 / AM4	L					9	21	1	101 113 123											
FM4 / AM4	Motor flange					E	35	E	35	В	14		B14							
FM5	L							1:	25	1	35		145		16	67	20	01		
гмэ	Motor flange							E	35	E	85		B14		B	14	B	14		
F14	L												145		10	65	19	79		
FJ1	Motor flange												B14		B	14	B	14		
E12	L									1	35		145		16	67	20	01	20	)3
FJ3	Motor flange									E	15		B5		В	5	В	5	В	15

For asynchronous motor specifications, see the motorization chapter (page 312).

If using ball screws (or trapezoidal screws with more than one input), together with the normal speed gearboxes (S) the FM/AM linear actuator may be reversible. Contact the NIASA technical department for the most suitable brake selection for your application.

In general, it is always advisable that the motors incorporate a brake, standard brakes are sufficient for each motor size in most cases. This will ensure the screw does not loose position when it stops or if there are vibrations, etc.





WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

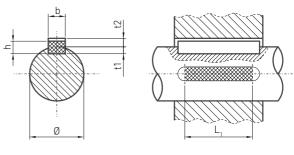
## MAXIMUM TRANSFERABLE TORQUE ACCORDING TO SHAFT/ PARALLEL COTTER PIN (DIN 6885)

The following table shows the maximum transferrable torque for a shaft and its keys. It is considered that the shaft is subject exclusively to torsional forces.

#### IMPORTANT

... Never subject the input of an FM Series actuator to torque over that indicated for its shaft

and keys (see plans in the sub-chapter "sizes", page 118).



Material: C45 (1.1191) according to EN 10083-1

please contact the NIASA technical department.

Load type: Drive - Uniform / Load - Slight knocks Assembly: tight Cycles: >1,000,000 Safety factor: 1.5 - 2.5

IMPORTANT For other conditions,

Shaft diameter	Key dimensions			/ Effective key length, L, (mm)							
Ø (mm)	b x h (mm)	t1 (mm)	t2 (mm)	10	16	20	28	40	50	70	
8 - 10	3 x 3	1.8	1.4	5	9	12	-	-	-	-	
10 - 12	4 x 4	2.5	1.8	9	13	17	-	-	-	-	
12 – 17	5 x 5	3	2.3	15	24	30	42	-	-	-	
17 – 22	6 x 6	3.5	2.8	25	40	50	70	100	-	-	
22 – 30	8 x 7	4	3.3	39	63	78	109	157	195	-	
30 – 38	10 x 8	5	3.3	50	82	102	143	204	255	357	

Maximum transferrable torque, M<sub>p</sub> (Nm)

# LUBRICATION

NIASA FM/AM Series linear actuators are supplied lubricated with DIVINOL LITHOGREASE G421 type grease. This is a semi-synthetic grease with a lithium compound with the following specifications,.

## Specifications

G421 DIVINOL LITHOGREASE						
Working temperature	-35 to +160°C					
Density at 15°C	0.9 kg/dm <sup>3</sup>					
Cinematic viscosity (s/DIN 51 562)	130 mm²/s at 40°C 15 mm²/s at 100°C					
Dropping point (s/DIN ISO 2176)	>220°C					
Water resistance (s/DIN 51 807/T1)	Level 1					

For further information, please contact the NIASA technical department.

NIASA supplies its FM/AM Series actuators with a brass lubrication cap with O-ring, on the gearbox and on the tube, to ensure it is sealed.

A change of grease type may affect the correct operation of the actuator.

There is a possibility of supplying FM/AM Series actuators with an angled grease nipple

at 45° DIN 71412 type B for the gearbox, and a straight grease nipple

DIN 71412 type A for the tube.

A complete cleaning and change of grease is recommended after five years.

The greasing interval depends on the type of work and its cycle. It is advisable to lubricate from 30 to 50 hours after start-up and approximately every six months. It is important to avoid over-lubricating.

A group lubricator is recommended for automatic lubrication of the units. Depending on the type of group lubricator, the lubrication may last up to two years. See lubrication chapter in accessories.



WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

## PROTECTION AGAINST CORROSION, SEALING AND AMBIENT TEMPERA-TURE

### **PROTECTION AGAINST CORROSION**

Select the environment in which the equipment will work, using the atmospheric corrosion categories classification established in the DIN EN ISO 12944-2 standard (protection against the corrosion of steel structures using painted systems). Also establish the durability required before carrying out the first maintenance of the exterior surfaces (durability does not imply a "time" guarantee).

If the corrosion category is higher than "C3" for your application and/or higher than "average" durability is required, please contact NIASA so that the technical department can select the surface protection system and select the most suitable components.

CORRO		ENVIRO	INMENT
CATEGO	DRY	Outdoors	Indoors
C1	Very low		Buildings with heating and clean atmospheres.
C2	Low	Atmospheres with low levels of pollution. Rural areas.	Buildings with no heating and possible condensation.
C3	Medium	Urban and industrial atmospheres, with moderate SO <sub>2</sub> pollution. Coastal areas with low salinity.	Manufacturing plants with high humidity and some pollution.
C4	High	Industrial areas and coastal areas with moderate salinity.	Chemical and swimming pool industries.
C5-I	Very high (industrial)	Industrial areas with high humidity and aggressive atmosphere.	Buildings or areas with almost permanent condensation and high contamination.
C5-M	Very high (maritime)	Coastal and maritime areas with high salinity.	Buildings or areas with permanent condensation and high contamination.

#### DURABILITY

LOW	L	2 to 5 years
MEDIUM	М	5 to 15 years
HIGH	Н	More than 15 years

#### PROTECTION AGAINST THE INPUT OF SOLIDS AND LIQUIDS

NIASA actuators offer, as standard, an IP65 protection index to prevent solid and liquid particles from entering the inside, which may damage them or reduce their designed service life.

Use the following table, according to the DIN EN IEC 60529 standard, if the level of protection must be higher than that indicated. NIASA supplies, on request, specially designed units to withstand the most aggressive environments.

The protection levels are defined with a code made up of the letters "IP" and two numbers "XY".

LEVEL OF PROTECTION "IP", AGAINST THE INPUT OF				
	solid particles: "X"	liquids: "Y"		
5	Protection against dust residues (the dust that may penetrate the inside does not imply incorrect operation of the equipment).	3	Protection against spray water (from angle up to 60° with vertical).	
6	Total protection against the penetration of any kind of solid body (sealing).	4	Protection against water splashes (from any direction).	
		5	Protection against water streams from any direction with hose.	
		6	Protection against sporadic floods (example: tidal wave).	

#### AMBIENT TEMPERATURE

Contact NIASA if your unit will be installed in an environment that may reach temperatures below -20°C and/or above +40°C.

NIASA's technical department will prescribe the most suitable materials and sealing components for the specific conditions of the application.

WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PRODUCT SELECTION**

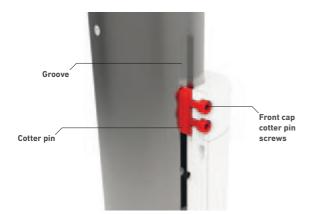
## **OPTIONAL CONFIGURATIONS**

Optionally, NIASA may adapt your FM/AM linear actuator, modifying the different parts of it to your preferences.

Some examples are shown below. See sub-chapter "Placing an order".

### Immobilizations

The FM Series electro-mechanical actuators, on request, can be supplied with the immobilized stem in rotation. This is achieved by mounting a key on the upper cap and machining a groove along the stem.



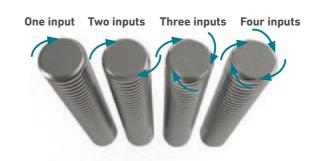
With this configuration, the scraper for the stem cannot be mounted on the front cap. To avoid the possible input of particles or liquid through the stem, it is recommended to mount a bellow to protect it.

For further information, please contact the NIASA technical department.



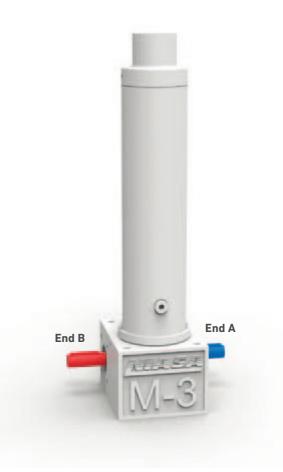
#### **Special configurations**

At the customer's request, the FM/AM Series linear actuators can be supplied with a screw of several inputs so that higher speeds can be obtained.



#### Worm gear

At the customer's request, the FM/AM linear actuators can be supplied with one of the sides of the worm shaft cut.





WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## **PLACING AN ORDER**

Example 01 02 03 04 05 06 07 08 09 10 11	01 02 03 04 05 06 07	SIZE FM1/AM1 FM2/AM2 FM3/AM3 FM4/AM4 FM5 FJ1 FJ3 GEARBOX S Normal speed H Slow speed EQUIPMENT GENERAL PROTECTI IPS Standard IP protection level IPS Special IP protection level IPS Special IP protection level SCREW TYPE (DIAMETER × PITCH TRS Steel trapezoidal screw KGS Ball screw STROKE 0000 Equipment usable stroke in IMMOBILISATION IN ROTATION 00 No immobilization 01 Immobilized STEM FASTENING ACCESSORY BPS Screw flange GKS Single rod GKB Double rod GIRBall joint FES Special end fastening 000 No accessory	D)	08 09 10 11	BOX FASTEN Always on the HFM Gearbox ZKM ZK gear ZKH ZK gear ZKY ZK gear FMS Special 000 No access EXTERIOR TU Exterior tube BA Trunnion All models FS Special fa 00 No access tilt ACCESSO SB With tilt s 00 No tilt sup LIMIT SWITC Exterior tube FCI Inductive FCR Inductive FCG Magneti All models 000 No limit	he back of t x fastening x mounting box fasteni box fasteni box fasteni gearbox fa- essory UBE FASTE configura mount with mount with mount with astening sory DRY support pport H ACCESS( configura limit switc) re limit switc ic limit swit	the box rod feet ing with b ing with 9 istening ENING ACC ation F h studs h ball bea ation A h studs	pearings 20° bolts CESSORY arings	
--	--	--	----	-------------	--	---	---	--	--

12	STEM PROTECTION ACCESSORY				
	Exterior tube configuration F FB Bellow type protector 00 No protector		G	<b>FRA</b> Standard lubricant <b>FRX</b> Lubricant for low extreme tempera <b>FRS</b> Other lubricant	atures
13 14	DRIVE ADAPTATION MK Standard flange MS Special drive union VE Wheel 00 No adaptation DRIVE POSITION ON GEARBOX A Worm shaft side A B Worm shaft side B			UBRICATION ACCESSORIES TP Sealed lubrication cap (standard) TA Angled lubricator on gearbox or st tube GR Automatic lubricating accessory 100 No lubricating accessory COUPMENT GENERAL COLOUR Vith type A configuration, only the gea	
15	STANDARD MOTOR MK drive adaptation 080 Group size A Power-1 / B Power-2 MS drive adaptation 1111 Non-standard drive Both adaptations		P R R R R C	Againted RGG Graphite grey RAL7024 (standard) RAZ Blue RAL5017 RGP Silver grey RAL9006 RSP Special colour indicated by the cus RIP Only grey 411 priming ROD Not painted	
16	0000       Without drive         WORM SHAFT END         A       Side A end suppressed         B       Side B end suppressed				
	0 Both sides maintained	FCCODY			
17	<ul> <li>Both sides maintained</li> <li>WORM SHAFT PROTECTION ACC</li> <li>PR With protector</li> <li>00 No protector</li> </ul>	ESSORY			
17	WORM SHAFT PROTECTION ACC PR With protector	ESSORY			
17	WORM SHAFT PROTECTION ACC PR With protector	ESSORY			
17 12 FB	WORM SHAFT PROTECTION ACC PR With protector 00 No protector	ESSORY 15 16 GR080A B		<b>17 18 19</b> 00 GRA AGR	<b>20</b> RGG

## NIASA

# **LINEAR ACTUATORS**

WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE | AM SERIES: ALUMINUM TUBE

## DISASSEMBLY

#### Name

01	M series box
02	Тор сар
03	Worm gear
04	Worm wheel
05	Lower cap
06	Exterior tube
07	Front cap
08	Stem
09	Tube position nut
10	Front support
11	Lock nut
12	Lock nut
13	Supplement bushing
14	Ball nut

\_\_\_\_

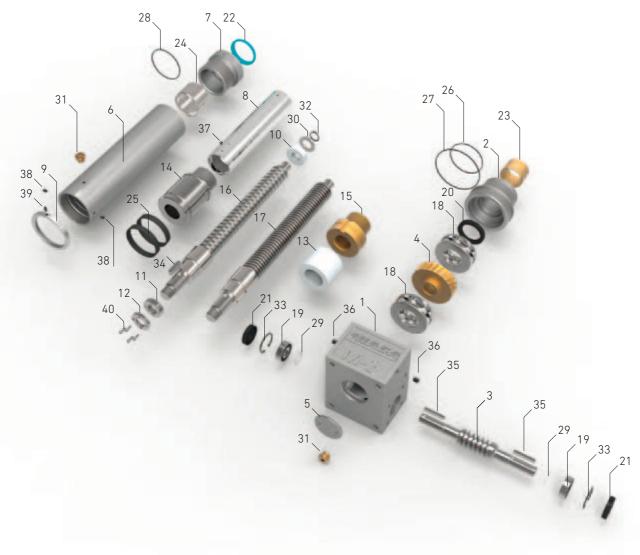
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15	Trapezoidal nut
16	Ball screw
17	Trapezoidal screw
18	Axial bearing
19	Radial bearing
20	Seal
21	Seal
22	Scraper
23	Bearing
24	Bearing
25	Guide ring
26	O-Ring
27	0-Ring
28	0-Ring

- 29 Adjustment washer
- 30 Flat washer
- 31 Brass lubrication cap
- 32 Exterior Circlip
- 33 Inside circlip
- 34 Straight key
- 35 Straight key
- 36 Stud with point
- 37 Flat stud
- 38 Stud with point
- 39 Flat stud
- 40 Allen screw





WITH INTEGRATED REDUCTION AND CUBIC GEARBOX. FM SERIES: STEEL TUBE  $\mid$  AM SERIES: ALUMINUM TUBE

## **SPECIAL CONFIGURATIONS**

